BWML Series

INSTRUCTION MANUAL

Thank you for choosing our Autonics product

Please read the following safety considerations before use

Safety Considerations

XPlease observe all safety considerations for safe and proper product operation to avoid hazards lepha symbol represents caution due to special circumstances in which hazards may occur.

∆Warning Failure to follow these instructions may result in serious injury or deat ▲Caution Failure to follow these instructions may result in personal injury or product damage.

⚠ Warning

- 1. Fail-safe device must be installed when using the unit with machinery that may cause serious injury or substantial economic loss. (e.g. nuclear power control, medical equipment, ships, vehicles, railways, aircraft, combustion apparatus, safety equipment, crime/disaster prevention devices, etc.)

 Failure to follow this instruction may result in personal injury
 2. Do not use the unit in the place where flammable/explosive/corrosive gas, high humidity, direct sunlight, radiant heat, vibration, impact, or salinity may be present.
- 3. Do not connect, repair, or inspect the unit while connected to a power source
- 4. Check the color of cables before wiring.
- 5. Do not disassemble or modify the unit.
- 6. This product is not safety sensor and does not observe any domestic nor international

safety standard.

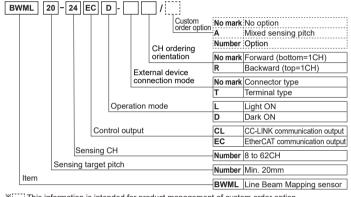
Do not use this product with the purpose of injury prevention or life protection, as well as in the place where economic loss maybe present.

⚠ Caution

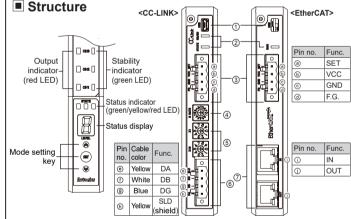
- 1. Use the unit within the rated specifications.
- 2. Use dry cloth to clean the unit, and do not use water or organic solvent.
- 3. Do not use a load over the range of rated relay specification.

or contact failure.

Ordering Information



*::::This information is intended for product management of custom order option (no need to refer when selecting model)



OUSB port:

Do not use this port for the another purpose, or the product can malfunction.

©Comm. status indicator: It displays the communication status through LED.

©Power cable connector

@Comm. speed setting switch (B RATE): You can set CC-LINK communication speed.

©Comm. address setting switch: You can set CC-LINK address. (X10: 10¹, X1: 10²)

©CC-LINK comm. connector

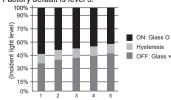
©EtherCAT comm. input/output connector: It is with the communication status indicator which turns on or flashes according to the communication status.

Function

○ Background sensing mode
This function instructs adjusting angle to install the product by displaying presence of the background object in the status display when installing the product. Use this function when sensing is unstable due to the reflection from the background object or any obstacle.

Installation guide mode
This function displays whether the sensing target is in the stable position of the guide line when installing the product through the output indicator. Entering installation guide mode and pressing less key starts teaching.

This function sets sensitivity by dividing receiving light into 5 levels for stable sensing. Use this function when some of the channels shows low sensing level due to the bent glass plate or diffused reflection. Factory default is level 5



Output option (Sensing level) utput ontion, press key to set additional ontion

Arter setting output option, press & key to set additional option.							
Output option (status display)	Description	Additional option	Output option (status display)	Description	Additional option		
0	Returning to operation mode	_	ч		Я: A point ь: В point		
1	Status display orientation	F : Forward	5	CC-LINK version	1: Ver 1.1 2: Ver 2.0		
2	Channel ordering	ь: Backward			1: 1 station 32 points 2: 2 station 64 points		
3	Operation mode	د : Light ON					

O Self-diagnosis

This function runs self-diagnose periodically in normal operation and displays the part in error at the status display when error occurs. (Refer to
 Operation Indicator'.)
 Channel interference alarm: Outputs alarm when interference from another sensing target

and external object in a channel area.

Disturbing light sensing alarm: Outputs alarm when the receiver received external light besides light from the emitter. When the amount of disturbing light is under the affective level, the product operates normally in disturbing light operation mode.

Emitter/Receiver damage alarm: Outputs alarm when emitter/receiver is damaged due to

the long-term usage of emitter/receiver elements or strong impact to the product *The above specifications are subject to change and some models may be discontinued

without notice.

**Be sure to follow cautions written in the instruction manual and the technical descriptions (catalog, homepage).

Autonics

Specific	cations					
Model	BWML	CL/_		BWML	EC/_	
Sensing type						
Sensing distance	95mm ±10mm					
Sensing target	Transparent	or opaque gla	ass plate			
Sensing area	280 to 1595	mm				
Sensing target pitch*1	20mm to					
Sensing CH ^{*1}	8 to 62CH	-	-			
CH ordering orientation	Forward (bottom=1CH) / Backward (top=1CH) (parameter setting)					
Beam pattern	Line beam type					
Power supply	24VDC== (ripple P-P: max. 10%)					
Protection circuit	Reverse polarity protection					
Current consumption						
Operation mode	Light ON/Dark ON (parameter setting)					
Response time	Max. 120ms					
	CC-LINK communication			EtherCAT communication		
	Version	CC-LINK Ver 1.1	CC-LINK Ver 2.0	Comm. protocol	EtherCAT protocol	
	Type of Station			Physical layer	100BASE-TX (IEEE802.3u)	
	Extended cyclic		1 time (single)	Comm. medium	Over CATEGORY 5/E (must be shield cable)	
	Number of 1 station 32 points module		Connection			

	Version	Ver 1.1	Ver 2.0	protocol	EtherCAI protocol
	Type of Station	Remote Device station		Physical layer	100BASE-TX (IEEE802.3u)
	Extended cyclic			Comm. medium	Over CATEGORY 5/E (must be shield cable)
Control output	Number of occupied stations	1 station 32 points module, 2 station 64 points module		Connection method	Daisy chain
Control output	Transmission speed	156kbps/625kbps/ 2.5Mbps/5Mbps/10Mbps		Transmission speed	100Mbps
	Max. number of connection*2	42 units		Address range	0 to 65535 (16-bit)
	Number of I/O points	1 station : 32 points (I/O allocation) 2 station : 64 points (I/O allocation)		Address setting	Software (EtherCAT Master)
			,	Comm. range	Distance between nods : max. 100m
Noise immunity	The square wave noise by the noise simulator (voltage: 500V, period: 10ms, pulse width: 1us)				
Dielectric strength	Between all power input terminals and F.G. terminal: 500VAC 50/60Hz for 1 min Between communication input terminals and F.G. terminal : 1000VAC 50/60Hz for 1 min Between power input terminals and communication input terminals : 1000VAC 50/60Hz for 1 min				
Insulation resistance	Over 20MΩ (at 500VDC megger)				
Vibration	1.5mm amplitude at frequency of 10 to 55Hz (for 1 min) in each X, Y, Z direction for 2 hours				

Allowable Allowable humi 15 to 35°C, storage: -10 to 50°C 35 to 55%RH, storage: 35 to 85%RH humi. Case: aluminum, sensing part and indicator part: polymethyl methacrylate Material Accessory Bracket A: 4, bracket B: 4, bolt: 8
Protection structure IP40 (IEC standard) C€, CC-LINK Approva Approx. 4.8kg (approx. 3.64kg) (based on BWML82-20ECL)

210m/s² (approx. 21G) in each X, Y, Z direction for 3 times

Shock

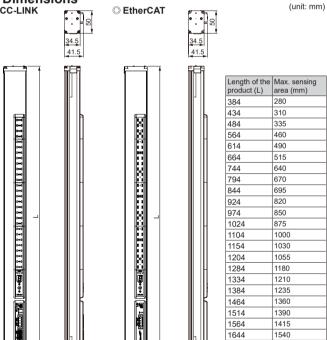
※1: This product is order made.
※2: The number of connectable units = 16×A+54×B+88×C≤2304
- A: remote I/O station, max. 64 units
- B: remote device station, max. 42 units

C: local, intelligent station, max. 26 units

direction for 2 hours

※3: The weight includes packaging. The weight in parenthesis in for unit only.
※Environment resistance is rated at no freezing or condensation.

Dimensions



Max. sensing area = 20+{sensing target pitch×(the total number of sensing target-1)}

1694

1570 1595

 Bracket B Bracket A 2-R2 \Ø7 ∖ø7 \2-R2 4-R1.6 2-R2 Ø24 4-R1.1 R2

Installation and Adjustment

①Install the product on the right side of the sensing target

the first glass of the full cassette is aligned with the installation guide line.

②Adjust the height of the product to the place where

Supply the power.Enter to the background sensing mode to detect background. If any background object is detected, reinstall the product, changing the installation angle

in any background object is detected, reinstall the product, training the installation, when all channels are turned on after placing full cassette.

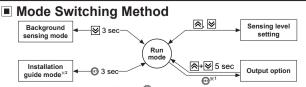
(i) If all channels are not turned on, enter to the installation guide mode and adjust the product up and down. Return to the run mode and finish installation, when all channels are turned on

Installation

★If there is disturbing light (fluorescent light) near the product, install the product vertically

away from the disturbing light (fluorescent light). XUse the product only for sensing the glass over the 6.5 generation.

If the product is used for sensing the glass under the 6.5 generation, the product can malfunction



※1: When the status display is ∅, press ⊕ key to return to the run mode.

Operation Timing Diagram OFF level /el light ↓ level Stable light OFF level (green LED) Output indicator (red LED) OFF CC-LINK or EtherCAT output OFF

**The waveforms of 'Operation indicator' and 'CC-LINK or EtherCAT output' are for Light ON. The waveforms are reversed for Dark ON.

CC-LINK Baud Rate and Address Setting

For CC-LINK setting, communication speed of PLC Master and BWML should be the same.
 Address is available from 1 to 64 and it should not be duplicated.
 When changing CC-LINK setting, turn OFF the power of this unit and re-supply the power.

Setting range 0: 156kbps, 1: 625kbps, 2: 2.5Mbps 3: 5Mbps, 4: 10Mbps, 5 to F: not used 0: Master, 01 to 64: settable address, 65 to 99: not used E.g.) To set 12 as address, set X10 to 1 and X1 to 2. B RATE Baud rate X10, X1 Address of unit

EtherCAT I/O DATA Structure

※HIGH: ON, LOW: OFF for bit status.					
Description	2nd Word	Description			
CH1 status	I/O0 [BIT0]	CH17 status			
CH2 status	I/O1 [BIT1]	CH18 status			
CH3 status	I/O2 [BIT2]	CH19 status			
CH4 status	I/O3 [BIT3]	CH20 status			
CH5 status	I/O4 [BIT4]	CH21 status			
CH6 status	I/O5 [BIT5]	CH22 status			
CH7 status	I/O6 [BIT6]	CH23 status			
CH8 status	I/O7 [BIT7]	CH24 status			
CH9 status	I/O8 [BIT8]	ERROR output BIT			
CH10 status	I/O9 [BIT9]	ALARM output BIT			
CH11 status					
CH12 status					
CH13 status					
CH14 status					
CH15 status					
CH16 status					
	Description CH1 status CH2 status CH3 status CH3 status CH4 status CH5 status CH6 status CH7 status CH8 status CH9 status CH9 status CH10 status CH11 status CH12 status CH15 status CH15 status CH15 status	Description			

Since the above is based on the product of 24 CH, the number of I/O is changeable by product.

EtherCAT I/O data structure consists of the number of CH+ERROR output BIT+ALARM output BIT.

BIT+ALARM outp

Operation Indicator

(⇔: light ON, ●: light OFF, ● CH indicator Output indicator (red LED) Stability indicator (green LED) Stable light ON Unstable light ON Unstable light OFF Stable light OFF

Status indicator

Item			Stability indicator		Status		Status	Communication cutout
		indicator (red LED)	(green LED)	Green	Yellow	Red	display	Communication output
Normal op	peration	_		≎	•	•	Sensing level	_
Background sensing	Sensed	ON (all CHs)	OFF (all CHs)	•	•	☼	ь	Outputting ON at All CHs outputting 'H' at N+1
mode	Not sensed	OFF (all CHs)	ON (all CHs)	₩	•	•	1	Outputting ON at All CHs
9	Optical axis coinciding CH	ON (LED of the CH)	ON (all CHs)	☼	•	•	n	
Installation guide mode	Optical axis not coinciding CH	OFF (LED of the CH)		•	•	•		Outputting ON at All CHs
ion gu	While teaching	OFF (all CHs)		☼	•	•	Flashing Ł twice	Outputting ON at All CHs
stallat	Teaching passed	Displaying result and		≎	•	•	Flashing twice	_
Ë	Teaching failed	Flashing alternately passed/failed CH twice		•	•	•	Flashing E twice	Outputting ON at All CHs outputting 'H' at N+1
Channel interference error		Flashing alternately relevant CH at 0.5 sec interval	ON (all CHs)	₩	•	•	_	Outputting ON at All CHs outputting 'H' at N+1
Disturbing light sensing alarm		Flashing alternately even and odd CH at 0.5 sec interval	ON (all CHs)	•	₩	₩	_	Outputting alternately even and odd CH, outputting 'H' at N+2
receiver damage	Emitter damage	ON (damaged CH)	ON (emitter)		• •	#	Е Ь	Outputting 'H' at emitter/ receiver damaged CH,
	Receiver damage	ON (CH 7, 8)	ON (receiver)	N (receiver)			~~	,
Comm. error	Product ↔ CH indicator	Flashing at 0.2	5 sec interval	•	•	•	Ε	Outputting ON at All CHs
	Product ↔ emitter/ receiver	Flashing (malfunctioning CH)	ON (CH 1)	•	₩	₩	٤	outputting 'H' at N+1

※1: If emitter and receiver are damaged at the same time, output of receiver is prior to that of emitter, and lower number of channel indicator is turned on. The indicator of damaged channel is flashed at 0.25 second interval.
※N stands for all channel.

Communication status indicator						
CC-LINK		Comm. status indicator				
STATE	RUN	ON (green LED)				
RD/SD	KUN	OFF				
STATE	Error	ON (red LED)				
RD/SD	EIIOI	ON (red/green/yellow LED)				
EtherCAT		Comm. status indicator (green LED)				
	Initial status	OFF				
RUN	Pre operation status	Flashing at 200ms interval				
KUN	Safe operation status	Repeating 200ms ON and 1000ms OFF				
	Operation status	ON				
	No connection	OFF				
L/A IN, L/A OUT	Operation status	Flashing at 50ms interval				
LACOI	Disconnection in operation	OFF				

■ Troubleshooting

	, on oo ang			
Malfunction	Cause	Troubleshooting		
Not operate	Power	Supply the rated power.		
	Cable cut, disconnection	Check the wiring.		
Not operate in sometimes	Sensor cover pollution by dirt	Remove dirt by soft brush or cloth and set sensitivity again.		
	Connector connection failure	Check the connection area of connector.		
Output is ON without a target	Initial sensitivity setting goes wrong	Remove the cause and set sensitivity again.		
	There is a strong electric wave or noise generator.	Put away motor, electric generator, or high voltage line.		

Cautions during Use

Follow instructions in 'Cautions during Use'. Otherwise, it may cause unexpected accidents.
 2. 24VDC power supply should be insulated and limited voltage/current or Class 2, SELV power supply

device.
3. Use the product, 1 sec after supplying power.

When using switching mode power supply to supply the power, ground F.G. terminal and connect a condenser between 0V and F.G. terminal to remove noise.
 When connecting a DC relay or other inductive load, remove surge by using diodes or varistors.
 Wire as short as possible and keep away from high voltage lines or power lines, to prevent surge and

inductive noise.
7. This unit may be used in the following environments.

②Altitude max. 2,000m

③Pollution degree 2④Installation category II

Major Products

Pulse (Rate) Meters

aser Marking System (Fiber, Co₂, Nd: YAG) aser Welding/Cutting System



454010 г. Челябинск, ул. Гагарина 5, оф. 507 тел. 8-800-775-09-57 (звонок бесплатный), тел.: (351)799-54-26, тел./факс (351)211-64-57 info@rusautomation.ru умустизационатизация.рф

**2: Entering to the installation guide mode and pressing key starts teaching, and the product returns to the run mode after teaching completed.