Autonics

LASER DISPLACEMENT SENSOR [AMPLIFIER UNIT] **BD SERIES**

INSTRUCTION MANUAL

Thank you for choosing our Autonics product.

Please read the following safety considerations before use.

Safety Considerations

XPlease observe all safety considerations for safe and proper product operation to avoid hazards. ★★ symbol represents caution due to special circumstances in which hazards may occur.

Marning Failure to follow these instructions may result in serious injury or death

▲ Caution Failure to follow these instructions may result in personal injury or product damage

⚠ Warning

- Fail-safe device must be installed when using the unit with machinery that may cause serious injury or substantial economic loss. (e.g. nuclear power control, medical equipment, ships, vehicles, railways, aircraft, combustion apparatus, safety equipment, crime/disaster prevention devices, etc.)
- Failure to follow this instruction may result in personal injury, economic loss or fire.

 2. Do not use the unit in the place where flammable/explosive/corrosive gas, humidity, direct sunlight, radiant heat, vibration, impact, or salinity may be present. Failure to follow this instruction may result in explosion or fire.
- 3. Do not disassemble or modify the unit.
- Failure to follow this instruction may result in fire
- A. Do not connect, repair, or inspect the unit while connected to a power source.
 Failure to follow this instruction may result in fire.
 Check 'Connections' before wiring. [Amplifier unit]
 Failure to follow this instruction may result in fire.

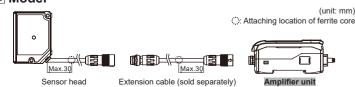
▲ Caution

- Do not stare at the laser emitter. [Sensor head]
 Failure to follow this instruction may result in eye damage.
 Use the unit within the rated specifications.
- Failure to follow this instruction may result in fire or product damage.

 3. Use dry cloth to clean the unit, and do not use water or organic solvent.
- Failure to follow this instruction may result in fire.

 4. Mount the ferrite core to specified position before using. [Sensor head, Extension cable] Failure to follow this instruction may result in output with noise

■ Model



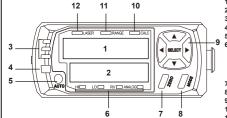
OSensor head

	Model	Beam shape	Reference distance (Maximum measurement range)	Spot diameter			
Mod				Near	Reference	Far	
BD-0	030	Standard	30mm (20-40mm)	Approx. 290×790µm (at 25mm)	Approx. 240×660µm (at 30mm)	Approx. 190×450µm (at 35mm)	
BD-0	065	Standard	65mm (50-80mm)	Approx. 360×1590μm (at 55mm)	Арргох. 290×1180µm (at 65mm)	Approx. 210×830µm (at 75mm)	
BD-1	100	Standard	100mm (70-130mm)	Арргох. 480×1870µm (at 80mm)	Approx. 410×1330μm (at 100mm)	Арргох. 330×950µm (at 120mm)	
©Aı	OAmplifier unit OExtension cable (sold separately)						

OAmplifier unit

Model	Compatible sensor head	Model	Length
BD-A1	BD series sensor head: 1	CID6P-1-SI-BD	1m
		CID6P-2-SI-BD	2m
		CID6P-5-SI-BD	5m
		CID6P-10-SI-BD) 10m

Unit Description



- Present value (PV) display: Red Setting value (SV) display: Green
- ent indicator: Red (HI/LO), Green (GO) Alarm indicator: Red
- Optimization setting key [AUTO] Setting value (SV) indicator recognition lamp: Green HI/LOW: HIGH/LOW judgment value
- RV: Real distance value ANALOG: Analog output
 Zero adjustment setting key [ZERO]
 Mode setting key [MODE]
- Direction key [◀/▶/▲/▼]
- 10 Calculation indicator (CALC): Green
- Measurement range indicator (RANGE): Green
 Laser emission indicator (LASER): Green

■ Display When Power is ON

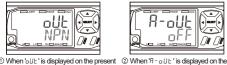
Displays control output setting screen when connecting a sensor head and supplying power at the first time, or replacing a sensor head. Set the output type as below sequence.

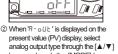
Refer to '**Parameter setting**' to check the setting range and the reset method.



value (PV) display, select control output

type through the [▲/▼] keys and push







times and it returns to the run mode

- keys and push the [MODE] key. The above specifications are subject to change and some models may be discontinued without
- Be sure to follow cautions written in the instruction manual, user manual and the technical descriptions (catalog, website).

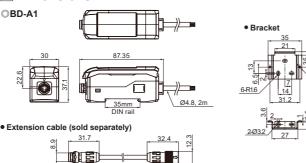
Specifications

Amplifier un	it			
Model		BD-A1		
Power supply		10-30VDC::. ±10% (When connecting BD-C Series communication converter, 12-30VDC::.)		
Power consur	mption ^{×1}	Max. 2800mW (30VDC::-)		
	Timing			
Control	Output reset			
input ^{×2}	Laser OFF	No-voltage input		
ii iput	Zero adjustment			
	Bank change			
Judgment out (HIGH/GO/LC		NPN or PNP open collector output (Load current: Max. 100mA)		
Alarm output		NPN or PNP open collector output (Load current: Max. 100mA)		
Analog outpu	.×3	Voltage: -5-5V, 0-5V, 1-5V (Resistance: 100Ω, ± 0.05% F.S., at 10V)		
Analog outpu		Current: 4-20mA (Max load resistance: 350Ω, ± 0.2% F.S., at 16mA)		
Residual volta	age	NPN: Max. 1.5V, PNP: Max. 2.5V		
Protection cir	cuit	Reverse polarity protection circuit, output overcurrent (short-circuit) protection circuit		
Response tim	ie	0.33, 0.5, 1, 2, 5 ms (5-step adjustment)		
Min. display u	nit	1μπ		
Display metho	od	Dual display by 6-digit, 11-segment LED		
Display range	×4	±99.999mm to ±99mm (4-step adjustment)		
Display perior	d	Approx. 100ms		
Insulation res	istance	Over 20MΩ (at 500VDC== megger)		
Noise immuni	ty	Square shaped noise by noise simulator (pulse width: 1µs) ±500V		
Dielectric stre	ngth	1,000VAC 50/60Hz for 1 minute		
Vibration		1.5mm amplitude at frequency of 10 to 55Hz (for 1 min) in each X, Y, Z direction for hours		
Shock		300m/s² (Approx. 30G) in each X, Y, Z direction for 3 times		
Environment	Ambient temperature	-10 to 50°C, storage: -15 to 60°C		
Environment	Ambient humidity	Under 85%RH, Storage: under 85%RH		
Protection str	ucture	IP40 (IEC Standards)		
Material		Case: Polycarbonate, Cover: Polycarbonate, Cable: Polyvinyl chloride		
Connection		Connector type		
Sensor head	compatibility	BD Series sensor head: 1		
Accessory		Mounting bracket, Side connector		
Approval		(€; ЯХ us		
Weight ^{×5}		Approx. 228g (approx. 126g)		
V:1: Dower to t	he load is not inclu			

- 1: Power to the load is not included

- ※1: Power to the load is not included.
 ※2: Use after assigning to external input line. For the details, refer to the item in '■ Parameter group'.
 ※3: It is possible to use among -5-5V, 0-5V, 1-5V, 4-20mA by parameter setting.
 ※4: Setting range is assigned automatically when connecting sensor head.
 ※5: The weight is with packaging and the weight in parenthesis is only unit weight.
 ※The temperature or humidity mentioned in Environment indicates a non freezing or condensation environment.

Dimensions



Installations

OMounting with bolt

Mounting without DIN rail is possible by using bracket. The method of mounting and detaching with bracket is as same as DIN rail.

Mounting on DIN rail Mounting



holder of amplifier unit to 35mm width DIN rail.

② Push the front part of the unit to arrow direction to mount.

 Detaching **a**

① Side amplifier unit to Pull the assembly part to (b) direction to

OConnecting to sensor head



① Connecting: Insert a connector of the sensor head into amplifier unit with aligning '†' mark and '▲' mark until it sounds click Disconnecting: Pull out the connector cap of sensor head to the opposite

*Do not supply the power when connecting or

OFerrite core

(accessory for sensor head, extension cable) Extension cable (sold separately)



Within 30mm from the connector of amplifier unit, wind the cable through the inside of the ferrite core three times and mount the ferrite core.



① Remove the side cover at the connecting side. ② Connect the side connector to the units.

3 After mounting amplifier unit on DIN rail, push it to arrow direction tightly XIn case of disconnecting, follow the upper sequence

Distinguishing master/slave amplifier units

When the power cable direction is down, the amplifier at the left end is the master unit, and the channel number increases sequentially to the right.

Slave

Mount on DIN rail.

. Do not supply the power when adding amplifier unit. Supply power to each connected amplifier unit at the same time Up to 8 amplifier units can be connected, and only 1 calculation function can be performed per 1 group of mutually connected

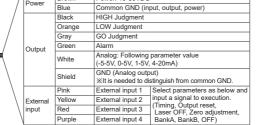
values (SV) of the slave units are disable and the mutual interference prevention function for sensor heads is executed automatically.

■ Manuals

For the detail information and instructions, please refer to user manual, and be sure to follow cautions written in the technical descriptions (catalog, website).

Connections Power: 10-30VD0 Blue HIGH Judgment Orange LOW Judgmer GO Judgment

Visit our website (www autonics com) to download manuals



Control Output Diagram

■ Parameter Setting

over 2 sec

within 2 sec

[▼] kev

Parameter group over 2 sec

Mode Key

Run mode

Sensing

Zero adjustment

adjustment (Teaching)

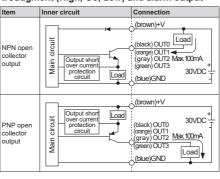
HIGH PEAK

LOW PEAK

HIGH sensitivity [MODE]+[▲]

LOW sensitivity adjustment | [MODE]+[▼] | key over 2 sec

OJudgment (High, Go, Low) and alarm output



Present value (PV) display

• Solo: Displays present value (PV).

color and environment.

(CALC) of master amplifier unit turns on.

When using calculation: Displays the result of calculation, and calculation indicate

Setting value(SV) display
Can change the type of value by the [4/ >] keys, and each recognition lamp turns on.

Setting range: HIGH setting value, LOW setting value, real distance value (RV), analog output, bank (Displays [bRNK - []) and all the recognition lamps turn off.)
Optimizes the level of laser emission and receiving sensitivity regarding the object

Sets the present value (PV) to the reference distance forcibly.

Execution: After entering the mode, push the [ZERO] key within 1 sec, or apply the signal to external input wire for zero adjustment over 3 sec.

Dismiss: Push the [ZERO]+[MODE] keys over 2 sec, or apply the signal to external

If the present value is changed by zero adjustment, the setting values (HIGH SV.

Can change the number of digit by the [◄/▶] keys, and setting value by the [▲/▼]

Enter the auto sensitivity adjustment setting mode after set the type of teaching mode

Sets the judgment output range by using present value (PV) of reference object height.

Sets the judgment output range by using present value (PV) of reterence object height. HIGH setting value=height present value+1.5 LOW setting value=height present value+2 Setting: 1. 1/P is displayed on setting value (SV) display, push the [AUTO] key within 2 sec. 2. After teaching the object for 2 sec, set the judgment output range automatically by applying the result.

2-point teaching
 Sets the judgment output range by using present value (PV) of reference object step.
 HIGH setting value=(step×1.5)+bottom height
 LOW setting value=(step+2)+bottom height
 Setting: 1.1P is displayed on setting value (SV) display, push the [AUTO] key within 2 sec.
 2. After teaching the object for 2 sec, 12P is displayed on setting value (SV)

After teaching the object for 2 sec, set the judgment output range automatically by applying the result.

ontrol output (3)E: NEN output (APA; PNP output PAP analog output (A-oUE): Disable (5FF), 4-20mA current output (4-20MA), 0 to 5V voltage output (2-5F), 1 to 5V voltage output (1-5F) -5 to 5V voltage output (-5-5)

After setting is finished, flashes 'פּעני פּעני on present value(PV) display and 'ENd' on

Displays HIGH/LOW PEAK value.

If there is direction key input or no key input for 5 sec, returns to run mode.

If push the [▲/▼] key over 3 sec during HIGH/LOW PEAK value display mode,

Setting: Select the setting value by $[\mathbf{A}/\mathbf{V}]$ key, and apply by [MODE] key.

ecution: Execute automatically when entering the mode

input wire of zero adjustment over 3 sec.

LOW SV etc.) are not changed.

Sets the judgment output (HIGH/GO/LOW) range by manual input.

keys.
The recognition lamps display the type of sensitivity adjustment.

Set the judgment output (HIGH/GO/LOW) range automatically.

display, push the [AUTO] key within 2 sec.

Setting range
control output 'hill-': NPN output 'NPN'. PNP output 'PNP'

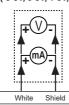
setting value (SV) display 3 times, and returns to run mode

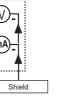
If there is no value, displays 'HHHH' / 'LLLL'.

Enters to the parameter group 1 to 4.

Sets the type of control/analog output

OAnalog output (-5-5V, 0-5V, 1-5V, 4-20mA)





■ Error Display

Parameter Group

Parameter group 1
PARR I Settings related to output type, displacement, display and error output.

Response time 330µs, 500µs, 1ms, 2ms, 5ms

dot Display digit 0.000, 0.00, 0.0, 0

нч5 Hysteresis | 0.001 to 99.999

PARRA3 Parameter group 3
Settings related to external input.
Parameter Setting range

SENS Teaching mode

NoNE Output type

dl 5P PV display

H-5E Display

ERROUL Error output

FI XDUE Fixed output

d-IN | External input 1

d-1 N2 Externa input 2

d-1 N3 External input 3

d-1 NY External input 4

Setting range

5ENd Standard 5ERLE Scale

-99.999 to 99.999

-99.999 to 99.999

FIX Fixed value

E - I N Timing input

UFFIR Output reset L-off Stop emission
ZERo Zero adjustme
BANK-A Bank input-A
BANK-B Bank input-B

Set analog output range

Push the [MODE] key over 2 sec to enter the parameter setting mode.

In the setting mode, change the parameter group by the $\lfloor 4/F \rfloor$ keys and enter the group by pushing the [MODE] key. In the group, change the parameter by the $\lfloor 4/F \rfloor$ keys, select it by pushing the [MODE] key, and change the setting

0.000

0.001

Max.

7FRn

Settings related to present value.

ter Setting range

off Off

Calculation Rdd-Rb Add

| RF | Average filter | dFF | Differential filter | BFF | Samples for | 1, 2, 4, 8, 16, 32, 64, 128, averaging | 256, 512, 1024, 2048, 4096 | Samples for | median | GFF, 3, 5, 7, 15, 31

Auto trigger -99.999 to 99.999

E-Mod Timer ond Output delay
oFd Output hold
EI ME Timer value 0 to 9999

PARRHY | Parameter group 4 | Settings related to user convenience function |
Parameter | Setting range |

[▲/▼] (select direction) → [MODE] (apply) ЬЯМК - Ū, ЬЯМК

BRNK-2, BRNK

SRVE I Digital display
SRVE2 All display

group `

| Reverse | Reve

Lock | [AUTO], [ZERO] Lock | [AUTO], [ZERO] +entering paramete

RLHY5 Auto trigger hysteresis 0.001 to 99.999

RV 5 Average mode

BOTTON
P-P Difference
SAMPLE Sample
RVS Average
E-IN External input
REUP Over auto trigger level
REUN Under auto trigger level

ΓRI Γ Calculation

681 N Gain

Hold Hold

ьямк Bank

Saving mode

Lock mode

Default

AVF

0.001

nFF

oFF

In the each step, push the [MODE] key over 3 sec to save and return to the upper step

ed on present value (PV) display

Setting value SV) display	Output	Reason	Solution	
нЕЯа	0	Disconnection of sensor head/amplifier unit/cable Sensor head malfunction	Check the connection between sensor head and amplifier unit. Check the disconnection of sensor head cable. Perform the above items and supply the power again.	
LASER	0	Malfunction of emission	If the problem is not resolved after the above items are performed, it judged that the sensor head is defective and needs to be replaced.	
d A R K		Not existing the object or background in maximum		
RANGE	_		Adjust the distance between sensor head and object in the maximur measurement range.	
PBI BHF	_	Over receive the light	·9	
	_	In status of display unavailable	Return to status of present value display available.	
Я-МЕМ	0		Turn off the power, check the connection of sensor head, and supply the power again. Executes the initialize " NI E' function. If the problem is not resolved after the above items are performed, it judged that the amplifier unit is defective and needs to be replaced.	
н-тЕп	0	Sensor head memory malfunction	Turn off the power, check the connection of sensor head, and supply the power again. If the problem is not resolved after the above item is performed, it is judged that the amplifier unit is defective and needs to be replaced.	
AMP-C	0	Poor connection between amplifier units.	Check the connection between amplifier units, and supply the power again.	
VER	0	Mismatch the version of firmware between sensor head and amplifier unit.	Please contact the Autonics technical advisory center.	
oUt	0	Disconnection of the judgement output	After turn off the power, check connection of HIGH (black) / GO (gray) / LOW (orange) wire, and supply the power again.	
RUto	_	Teaching failure	After check the object is in the maximum measurement range, execute again.	
ЯМР	0	Amplifier unit error	After turn off the power, check the connection of sensor head, and supply the power again. If the problem is not resolved after the above items are performed, it judged that the amplifier unit is defective and needs to be replaced.	
o£UR	0	Over current of output terminal	Check the load of output is specification range. Check the output is contacted other wire or frame.	

■ Cautions during Use

- 1. Follow instructions in 'Cautions during Use'. Otherwise, it may cause unexpected accidents.

 2. The power supply should be insulated and limited voltage/current or Class 2, SELV power supply device.

 3. Do not install where strong magnetic or electric field exist. Otherwise, the resolution may be adversely affected.

 4. Mutual optical interference between laser sensors and photoelectric sensors may result in malfunction.

 5. Mutual optical interference between laser sensors may result in malfunction and interference between laser sensors may result in malfunction.

 6. When connecting DC relay or other inductive load to the output, remove surge by using diode or varistor.

 7. Wire as short as possible and keep away from high voltage lines or power lines, to prevent surge and inductive noise (Ampolifier until
- [Amplifier unit]
 For the optimized performance, it is recommended to measure after 30 minute from supplying power. [Amplifier unit] n. Since external disturbance light (sunlight, fluorescent lighting, etc.) can cause product malfunction, use the product with a light shield or slit. [Sensor head]
- a myn. snieru or sini. [Jeetistor riedur]

 0. When detecting with the maximum sensitivity, an error may occur depending on each characteristic deviation.

 1. This unit may be used in the following environments.

 Olndoors/Outdoors (in the environment condition rated in 'Specifications')

 (②Altitude max. 2,000m

 OPullution degree 2

- 3Pollution degree 2

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